Package: cirls (via r-universe)

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Title Constrained Iteratively Reweighted Least Squares
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Description Routines to fit generalized linear models with constrained coefficients, along with inference on the coefficients. Designed to be used in conjunction with the base glm()

function. License GPL (>= 3)

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check_cmat

Description

Checks a constraint matrix does not contains redundant rows

Usage

check_cmat(Cmat)

Arguments

Cmat

A constraint matrix as passed to cirls.fit()

Details

The user typically doesn't need to use check_cmat as it is internally called by cirls.control(). However, it might be useful to undertsand if Cmat can be reduced for inference purpose. See the note in confint.cirls().

A constraint matrix is irreducible if no row can be expressed as a *positive* linear combination of the other rows. When it happens, it means the constraint is actually implicitly included in other constraints in the matrix and can be dropped. Note that this a less restrictive condition than the constraint matrix having full row rank (see some examples).

The function starts by checking if some constraints are redundant and, if so, checks if they underline equality constraints. In the latter case, the constraint matrix can be reduced by expressing these constraints as a single equality constraint with identical lower and upper bounds (see cirls.fit()).

Value

A list with two elements:

redundant	Vector of indices of redundant constraints
equality	Indicates which constraints are part of an underlying equality constraint

References

Meyer, M.C., 1999. An extension of the mixed primal–dual bases algorithm to the case of more constraints than dimensions. *Journal of Statistical Planning and Inference* **81**, 13–31. doi:10.1016/S03783758(99)000257

See Also

confint.cirls()

cirls.control

Examples

```
# Example of reducible matrix
# Constraints: successive coefficients should increase and be convex
p <- 5
cmatic <- rbind(diff(diag(p)), diff(diag(p), diff = 2))</pre>
# Checking indicates that constraints 2 to 4 are redundant.
# Intuitively, if the first two coefficients increase,
# then convexity forces the rest to increase
check_cmat(cmatic)
# Check without contraints
check_cmat(cmatic[-(2:4),])
*****
# Example of irreducible matrix
# Constraints: coefficients form an S-shape
p <- 4
cmats <- rbind(</pre>
 diag(p)[1,], # positive
 diff(diag(p))[c(1, p - 1),], # Increasing at both end
 diff(diag(p), diff = 2)[1:(p/2 - 1),], # First half convex
 -diff(diag(p), diff = 2)[(p/2):(p-2),] # second half concave
)
# Note, this matrix is not of full row rank
qr(t(cmats))$rank
all.equal(cmats[2,] + cmats[4,] - cmats[5,], cmats[3,])
# However, it is irreducible: all constraints are necessary
check_cmat(cmats)
*****
# Example of underlying equality constraint
# Contraint: Parameters sum is >= 0 and sum is <= 0</pre>
cmateq <- rbind(rep(1, 3), rep(-1, 3))</pre>
# Checking indicates that both constraints imply equality constraint (sum == 0)
check_cmat(cmateq)
```

cirls.control Parameters controlling CIRLS fitting

Description

Internal function controlling the glm fit with linear constraints. Typically only used internally by cirls.fit, but may be used to construct a control argument.

Usage

```
cirls.control(epsilon = 1e-08, maxit = 25, trace = FALSE, Cmat = NULL,
    lb = 0L, ub = Inf, qp_solver = "osqp", qp_pars = list())
```

Arguments

epsilon	Positive convergence tolerance. The algorithm converges when the relative change in deviance is smaller than epsilon.
maxit	Integer giving the maximal number of CIRLS iterations.
trace	Logical indicating if output should be produced for each iteration.
Cmat	Constraint matrix specifying the linear constraints applied to coefficients. Can also be provided as a list of matrices for specific terms.
lb, ub	Lower and upper bound vectors for the linear constraints. Identical values in 1b and ub identify equality constraints. Recycled if length is different than the number of constraints defined by Cmat.
qp_solver	The quadratic programming solver. One of "osqp", "quadprog" or "coneproj".
qp_pars	List of parameters specific to the quadratic programming solver. See respective packages help.

Details

The control argument of glm is by default passed to the control argument of cirls.fit, which uses its elements as arguments for cirls.control: the latter provides defaults and sanity checking. The control parameters can alternatively be passed through the ... argument of glm. See glm.control for details on general GLM fitting control, and cirls.fit for details on arguments specific to constrained GLMs.

Value

A named list containing arguments to be used in cirls.fit.

See Also

the main function cirls.fit, and glm.control.

Examples

```
# Simulate predictors and response with some negative coefficients
set.seed(111)
n <- 100
p <- 10
betas <- rep_len(c(1, -1), p)
x <- matrix(rnorm(n * p), nrow = n)
y <- x %*% betas + rnorm(n)
# Define constraint matrix (includes intercept)
# By default, bounds are 0 and +Inf
Cmat <- cbind(0, diag(p))</pre>
```

cirls.fit

```
# Fit GLM by CIRLS
res1 <- glm(y ~ x, method = cirls.fit, Cmat = Cmat)
coef(res1)
# Same as passing Cmat through the control argument
res2 <- glm(y ~ x, method = cirls.fit, control = list(Cmat = Cmat))
identical(coef(res1), coef(res2))</pre>
```

```
cirls.fit
```

```
Constrained Iteratively Reweighted Least-Squares
```

Description

Fits a generalized linear model with linear constraints on the coefficients through a Constrained Iteratively Reweighted Least-Squares (CIRLS) algorithm. This function is the constrained counterpart to glm.fit and is meant to be called by glm through its method argument. See details for the main differences.

Usage

```
cirls.fit(x, y, weights = rep.int(1, nobs), start = NULL,
etastart = NULL, mustart = NULL, offset = rep.int(0, nobs),
family = stats::gaussian(), control = list(), intercept = TRUE,
singular.ok = TRUE)
```

Arguments

х, у	x is a design matrix and y is a vector of response observations. Usually internally computed by glm.
weights	An optional vector of observation weights.
start	Starting values for the parameters in the linear predictor.
etastart	Starting values for the linear predictor.
mustart	Starting values for the vector or means.
offset	An optional vector specifying a known component in the model. See model.offset.
family	The result of a call to a family function, describing the error distribution and link function of the model. See family for details of available family functions.
control	A list of parameters controlling the fitting process. See details and cirls.control.
intercept	Logical. Should an intercept be included in the null model?
singular.ok	Logical. If FALSE, the function returns an error for singular fits.

Details

This function is a plug-in for glm and works similarly to glm.fit. In addition to the parameters already available in glm.fit, cirls.fit allows the specification of a constraint matrix Cmat with bound vectors lb and ub on the regression coefficients. These additional parameters can be passed through the control list or through ... in glm.

The CIRLS algorithm is a modification of the classical IRLS algorithm in which each update of the regression coefficients is performed by a quadratic program (QP), ensuring the update stays within the feasible region defined by Cmat, 1b and ub. More specifically, this feasible region is defined as $1b \leq Cmat %*\%$ coefficients $\leq ub$

where coefficients is the coefficient vector returned by the model. This specification allows for any linear constraint, including equality ones.

Specifying Cmat, 1b and ub:

Cmat is a matrix that defines the linear constraints. If provided directly as a matrix, the number of columns in Cmat must match the number of coefficients estimated by glm. This includes all variables that are not involved in any constraint potential expansion such as factors or splines for instance, as well as the intercept. Columns not involved in any constraint will be filled by 0s.

Alternatively, it may be more convenient to pass Cmat as a list of constraint matrices for specific terms. This is advantageous if a single term should be constrained in a model containing many terms. If provided as a list, Cmat is internally expanded to create the full constraint matrix. See examples of constraint matrices below.

lb and ub are vectors defining the bounds of the constraints. By default they are set to \emptyset and Inf, meaning that the linear combinations defined by Cmat should be positive, but any bounds are possible. When some elements of lb and ub are identical, they define equality constraints. Setting lb = -Inf and ub = Inf disable the constraints.

Quadratic programming solvers:

The function cirls.fit relies on a quadratic programming solver. Several solver are currently available.

- "osqp" (the default) solves the quadratic program via the Alternating Direction Method of Multipliers (ADMM). Internally it calls the function solve_osqp.
- "quadprog" performs a dual algorithm to solve the quadratic program. It relies on the function solve.QP.
- "coneproj" solves the quadratic program by a cone projection method. It relies on the function qprog.

Each solver has specific parameters that can be controlled through the argument qp_pars. Sensible defaults are set within cirls.control and the user typically doesn't need to provide custom parameters.

Value

A cirls object inheriting from the class glm. At the moment, two non-standard methods specific to cirls objects are available: vcov.cirls to obtain the coefficients variance-covariance matrix and confint.cirls to obtain confidence intervals. These custom methods account for the reduced degrees of freedom resulting from the constraints, see vcov.cirls and confint.cirls. Any method for glm objects can be used, including the generic coef or summary for instance.

An object of class cirls includes all components from glm objects, with the addition of:

active.cons	vector of indices of the active constraints in the fitted model.
inner.iter	number of iterations performed by the last call to the QP solver.
Cmat, lb, ub	the (expanded) constraint matrix, and lower and upper bound vectors

References

Goldfarb, D., Idnani, A., 1983. A numerically stable dual method for solving strictly convex quadratic programs. *Mathematical Programming* **27**, 1–33. doi:10.1007/BF02591962

Meyer, M.C., 2013. A Simple New Algorithm for Quadratic Programming with Applications in Statistics. *Communications in Statistics - Simulation and Computation* **42**, 1126–1139. doi:10.1080/03610918.2012.659820

Stellato, B., Banjac, G., Goulart, P., Bemporad, A., Boyd, S., 2020. OSQP: an operator splitting solver for quadratic programs. *Math. Prog. Comp.* **12**, 637–672. doi:10.1007/s12532020001792

See Also

vcov.cirls, confint.cirls for methods specific to cirls objects. cirls.control for fitting parameters specific to cirls.fit. glm for details on glm objects.

Examples

```
****
# Simple non-negative least squares
# Simulate predictors and response with some negative coefficients
set.seed(111)
n <- 100
p <- 10
betas <- rep_len(c(1, -1), p)
x <- matrix(rnorm(n * p), nrow = n)</pre>
y <- x %*\% betas + rnorm(n)
# Define constraint matrix (includes intercept)
# By default, bounds are 0 and +Inf
Cmat <- cbind(0, diag(p))</pre>
# Fit GLM by CIRLS
res1 <- glm(y ~ x, method = cirls.fit, Cmat = Cmat)</pre>
coef(res1)
# Same as passing Cmat through the control argument
res2 <- glm(y ~ x, method = cirls.fit, control = list(Cmat = Cmat))</pre>
identical(coef(res1), coef(res2))
****
# Increasing coefficients
# Generate two group of variables: an isotonic one and an unconstrained one
set.seed(222)
```

```
x1 <- matrix(rnorm(100 * p1), 100, p1)</pre>
x2 <- matrix(rnorm(100 * p2), 100, p2)
# Generate coefficients: those in b1 should be increasing
b1 <- runif(p1) |> sort()
b2 <- runif(p2)</pre>
# Generate full data
y <- x1 %*% b1 + x2 %*% b2 + rnorm(100, sd = 2)
#---- Fit model
# Create constraint matrix and expand for intercept and unconstrained variables
Ciso <- diff(diag(p1))</pre>
Cmat <- cbind(0, Ciso, matrix(0, nrow(Ciso), p2))</pre>
# Fit model
resiso <- glm(y ~ x1 + x2, method = cirls.fit, Cmat = Cmat)</pre>
coef(resiso)
# Compare with unconstrained
plot(c(0, b1, b2), pch = 16)
points(coef(resiso), pch = 16, col = 3)
points(coef(glm(y ~ x1 + x2)), col = 2)
#---- More convenient specification
# Cmat can be provided as a list
resiso2 <- glm(y ~ x1 + x2, method = cirls.fit, Cmat = list(x1 = Ciso))</pre>
# Internally Cmat is expanded and we obtain the same result
identical(resiso$Cmat, resiso2$Cmat)
identical(coef(resiso), coef(resiso2))
#----- Adding bounds to the constraints
# Difference between coefficients must be above a lower bound and below 1
lb <- 1 / (p1 * 2)
ub <- 1
# Re-fit the model
resiso3 <- glm(y ~ x1 + x2, method = cirls.fit, Cmat = list(x1 = Ciso),</pre>
  1b = 1b, ub = ub)
# Compare the fit
plot(c(0, b1, b2), pch = 16)
points(coef(resiso), pch = 16, col = 3)
points(coef(glm(y ~ x1 + x2)), col = 2)
points(coef(resiso3), pch = 16, col = 4)
```

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coef_simu

coef_simu

Simulate coefficients, calculate Confidence Intervals and Variance-Covariance Matrix for a cirls object.

Description

confint computes confidence intervals for one of more parameters in a GLM fitted via cirls.fit. vcov compute the variance-covariance matrix of the parameters. Both methods are based on coef_simu that simulates coefficients from a Truncated Multivariate Normal distribution. These methods supersede the default confint and vcov methods for cirls objects.

Usage

```
coef_simu(object, nsim = 1000)
## S3 method for class 'cirls'
confint(object, parm, level = 0.95, nsim = 1000, ...)
## S3 method for class 'cirls'
vcov(object, nsim = 1000, ...)
```

Arguments

object	A fitted cirls object.
nsim	The number of simulations to consider. Corresponds to n in rtmvnorm. See details().
parm	A specification of which parameters to compute the confidence intervals for. Either a vector of numbers or a vector of names. If missing, all parameters are considered.
level	The confidence level required.
	Further arguments passed to or from other methods. Currently ignored.

Details

These functions are custom methods for cirls objects to supersede the default methods used for glm objects.

Both methods rely on the fact that $C\hat{\beta}$ (with C the constraint matrix) follows a *Truncated Multi-variate Normal* distribution

$$C\hat{\beta} \sim TMVN(C\beta, CVC^T), l, u$$

where TMVN represents a truncated Multivariate Normal distribution. C is the constraint matrix (object\$control\$Cmat) with bound l and u, while V is the unconstrained variance-covariance matrix (such as returned by vcov.glm).

coef_simu simulates from the TMVN above and transforms back the realisations into the coefficients space. These realisations are then used by the confint and vcov methods which compute empirical quantiles and variance-covariance matrix, respectively. coef_simu is called internally by confint and vcov and doesn't need to be used directly, but it can be used to check other summaries of the coefficients distribution.

Value

For confint, a two-column matrix with columns giving lower and upper confidence limits for each parameter.

For vcov, a matrix of the estimated covariances between the parameter estimates of the model.

For coef_simu, a matrix with nsim rows containing simulated coefficients.

Note

These methods only work when Cmat is of full row rank. If not the case, Cmat can be inspected through check_cmat().

References

Geweke, J.F., 1996. Bayesian Inference for Linear Models Subject to Linear Inequality Constraints, in: Lee, J.C., Johnson, W.O., Zellner, A. (Eds.), Modelling and Prediction Honoring Seymour Geisser. *Springer, New York, NY*, pp. 248–263. doi:10.1007/9781461224143_15

Botev, Z.I., 2017, The normal law under linear restrictions: simulation and estimation via minimax tilting, *Journal of the Royal Statistical Society, Series B*, **79** (1), pp. 1–24.

See Also

rtmvnorm for the underlying routine to simulate from a TMVN. check_cmat() to check if the contraint matrix can be reduced.

Examples

```
*****
# Isotonic regression
#---- Perform isotonic regression
# Generate data
set.seed(222)
p1 <- 5; p2 <- 3
x1 <- matrix(rnorm(100 * p1), 100, p1)</pre>
x2 <- matrix(rnorm(100 * p2), 100, p2)
b1 <- runif(p1) |> sort()
b2 <- runif(p2)
y <- x1 %*% b1 + x2 %*% b2 + rnorm(100, sd = 2)
# Fit model
Ciso <- diff(diag(p1))</pre>
resiso <- glm(y ~ x1 + x2, method = cirls.fit, Cmat = list(x1 = Ciso))</pre>
#---- Extract uncertainty
# Extract variance covariance
vcov(resiso)
# Extract confidence intervals
```

coef_simu

confint(resiso)

We can extract the usual unconstrained vcov summary(resiso)\$cov.scaled all.equal(vcov(resiso), summary(resiso)\$cov.scaled)

Simulate from the distribution of coefficients
sims <- coef_simu(resiso, nsim = 10)</pre>

Check that all simulated coefficient vectors are feasible
apply(resiso\$Cmat %*% t(sims) >= resiso\$lb, 2, all)

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